

The perceptron algorithm

• The perceptron algorithm can be

online update weights for a single misclassified example batch updates weights for all misclassified examples at once

- The perceptron algorithm converges to the global minimum if the classes are *linearly separable*
- If the classes are not linearly separable, the perceptron algorithm will not stop
- We do not know whether the classes are linearly separable or not before the algorithm converges
- In practice, one can set a stopping condition, such as
 - Maximum number iterations/updates
 - Number of misclassified examples
 - Number of iterations without improvement

Learning with perceptron

- We do not update the parameters if classification is correct
- For misclassified examples, we try to minimize

$$\mathsf{E}(w) = -\sum_{i} w \mathbf{x}_{i} \mathbf{y}_{i}$$

- where i ranges over all misclassified examples
- · Perceptron algorithm updates the weights such that

$$w \leftarrow w - \eta \nabla E(w)$$

 $w \leftarrow w + \eta \mathbf{x}_i \mathbf{y}_i$

for misclassified examples. η is the learning rate



- The perceptron was developed in late 1950's and early 1960's (Rosenblatt 1958)
- It caused excitement in many fields including computer science, artificial intelligence, cognitive science
- The excitement (and funding) died away in early 1970's (after the criticism by Minsky and Papert 1969)
- The main issue was the fact that the perceptron algorithm cannot handle problems that are not linearly separable

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linear models

natural extension to multiple classes

- In logistic regression, we fit a model that predicts $\mathsf{P}(\boldsymbol{y}\,|\,\boldsymbol{x})$

• Typically formulated for binary classification, but it has a

maximum-entropy model (or max-ent) in the NLP literature

• The multi-class logistic regression is often called

- it is a member of the family of models called generalized

• Logistic regression is an extension of linear regression







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Logistic function



How to fit a logistic regression model (2)

- Bad news: there is no analytic solution
- Good news: the (negative) log likelihood is a convex function

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- We can use iterative methods such as gradient descent to find parameters that maximize the (log) likelihood
- · Using gradient descent, we repeat

 $\boldsymbol{w} \leftarrow \boldsymbol{w} - \eta \nabla E(\boldsymbol{w})$

until convergence, η is the *learning rate*

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Another example



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Fixing the outcome: transforming the output variable

- The prediction we are interested in is $\hat{y} = P(y = 1|x)$
- We transform it with logit function:

$$logit(\hat{y}) = \log \frac{\hat{y}}{1 - \hat{y}} = w_0 + w_1 x$$

- $\frac{\hat{y}}{1-\hat{y}}$ (odds) is bounded between 0 and ∞
- $\log \frac{\hat{y}}{1-\hat{y}}$ (log odds) is bounded between $-\infty$ and ∞
- we can estimate $logit(\hat{y})$ with regression, transform with the inverse of logit()

$$\hat{y} = \frac{e^{w_0 + w_1 x}}{1 + e^{w_0 + w_1 x}} = \frac{1}{1 + e^{-w_0 - w_1 x}}$$

which is called logistic (sigmoid) function

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How to fit a logistic regression model with maximum-likelihood estimation

$$P(y = 1 | x) = p = \frac{1}{1 + e^{-wx}} \qquad P(y = 0 | x) = 1 - p = \frac{e^{-wx}}{1 + e^{-wx}}$$

The likelihood of the training set is,

$$\mathcal{L}(\boldsymbol{w}) = \prod_{i} p^{y_i} (1-p)^{1-y_i}$$

In practice, we maximize \log likelihood, or minimize ' $-\log$ likelihood':

$$-\log \mathcal{L}(\boldsymbol{w}) = -\sum_i y_i \log p + (1-y_i) \log(1-p)$$

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Example logistic-regression back to the example with a single predictor





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Multi-class logistic regression

- · Generalizing logistic regression to more than two classes is straightforward
- We estimate,

$$\mathsf{P}(\mathsf{C}_k \,|\, \mathsf{x}) = \frac{e^{\boldsymbol{w}_k \mathsf{x}}}{\sum_j e^{\boldsymbol{w}_j \mathsf{x}}}$$

where C_k is the kth class, j iterates over all classes.

- The function is called the *softmax* function, used frequently in neural network models as well
- This model is also known as log-linear model, maximum entropy model, or Boltzmann machine

Naive Bayes classifier

- · Naive Bayes classifier is a well-known simple classifier
- It was found to be effective on a number tasks, primarily in document classification

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- Popularized by practical spam detection applications
- Naive part comes from a strong independence assumption
- Bayes part comes from use of Bayes' formula for inverting conditional probabilities
- However, learning is (typically) 'not really' Bayesian

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Naive Bayes: estimation (cont.)

• Class distribution, P(y), is estimated using the MLE on the training set

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- With many features, $\mathbf{x} = (x_1, x_2, \dots x_n)$, $P(\mathbf{x} | \mathbf{y})$ is difficult to estimate
- · Naive Bayes estimator makes a conditional independence assumption: given the class, we assume that the features are independent of each other

$$P(x \,|\, y) = P(x_1, x_2, \dots x_n \,|\, y) = \prod_{i=1}^n P(x_i \,|\, y)$$

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Naive Bayes

a simple example: spam detection

Training data:	D(0) 2/5 D(0) 2/5			
features present	label	P(S) = 3/5, P(NS) = 2/5		
good book	NS S NS S	w	$P(w \mid S)$	P(w NS)
now book free medication lose weight technology advanced book now advanced technology		medication	1/3	0
		free	1/3	0
		technology	1/3	1/2
		advanced	1/3	1/2
-		book	1/3	2/2
		now	2/3	0
• A test instance: {book,		lose	1/3	0
technology}		weight	1/3	0
 Another one: {good, 		good	0	1/2
medication}				

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More than two classes

- · Some algorithms can naturally be extended to handle multiple class labels
- Any binary classifier can be turned into a k-way classifier by
- OvR one-vs-rest or one-vs-all
 - train k classifiers: each learns to discriminate one of the
 - classes from the others · at prediction time the classifier with the highest confidence wins
 - needs confidence score from the base classifiers
- OvO one-vs-one
 - train $\frac{k(k-1)}{2}$ classifiers: each learns to discriminate a pair of classes
 - decision is made by (weighted) majority vote
 - works without need for confidence scores, but needs more classifiers

Naive Bayes: estimation

- Given a set of features x, we want to know the class y of the object we want to classify
- At prediction time we pick the class, ŷ

 $\hat{y} = \operatorname*{arg\,max}_{y} P(y \mid \boldsymbol{x})$

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· Instead of directly estimating the conditional probability, we invert it using the Bayes' formula

$$\hat{y} = \operatorname*{arg\,max}_{y} \frac{P(x \,|\, y) P(y)}{P(x)} = \operatorname*{arg\,max}_{y} P(x \,|\, y) P(y)$$

+ Now the task becomes estimating $\mathsf{P}(x\,|\,y)$ and $\mathsf{P}(y)$

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Naive Bayes: estimation (cont.)

- The probability distributions $P(x_i | y)$ and P(y) are typically estimated using MLE (count and divide)
- · A smoothing technique may be used for unknown features (e.g., words)
- Note that $P(x_i | y)$ can be

binomial e.g, whether a word occurs in the document or not categorical e.g, estimated using relative frequency of words continuous the data is distributed according to a known distribution

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Classifying classification methods another short digression

- · Some classification algorithms are non-probabilistic, discriminative: they return a label for a given input. Examples: perceptron, SVMs, decision trees
- · Some classification algorithms are discriminative, probabilistic: they estimate the conditional probability distribution p(c | x) directly. Examples: logistic regression, (most) neural networks

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· Some classification algorithms are generative: they estimate the joint distribution p(c, x). Examples: naive Bayes, Hidden Markov Models, (some) neural models

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One vs. Rest

χ_2 \oplus \oplus \oplus \oplus χ₁

- For 3 classes, we fit 3 classifiers separating one class from the rest
- Some regions of the feature space will be ambiguous
- We can assign labels based on probability or weight value, if classifier returns one
- One-vs.-one and majority voting is another option



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More classification methods ...

- · Classification is a well-studied topic in ML, with a large range of applications
- There are many different approaches
- In most cases you can 'plug' a classification algorithm instead of another, treating classifiers as 'black boxes'
- You should, however, understand the methods you use: you may not be able to use them properly if you do not understand them
- · One-slide introduction to some of the methods we did not cover starts on the next slide
- · We will return to some specialized methods later in this course

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Maximum-margin methods (e.g., SVMs)



• In perceptron, we stopped whenever we found a linear discriminator

- Maximum-margin classifiers seek a discriminator that maximizes the margin
- SVMs have other interesting properties, and they have been one of the best 'out-of-the-box' classifiers for many problems

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A quick survey of some solutions Instance/memory based methods



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Measuring success in classification Accuracy

• In classification, we do not care (much) about the average of the error function

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- · We are interested in how many of our predictions are correct
- Accuracy measures this directly

number of correct predictions accuracy = total number of predictions

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A quick survey of some solutions Decision trees



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A quick survey of some solutions Artificial neural networks



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Accuracy may go wrong

- Think about a 'dummy' search engine that always returns an empty document set (no results found)
- If we have
 - 1000000 documents

- 1000 relevant documents (related to the terms in the query) the accuracy is:

$$\frac{999\,000}{1\,000\,000} = 99.90\,\%$$

• In general, if our class distribution is skewed, of imbalanced, accuracy will be a bad indicator of success

Measuring success in classification

Precision, recall, F-score



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Classifier evaluation: another example

Consider the following two classifiers:

		true value			true value		
g		positive	negative		positive	negative	
predicte	pos.	7	9		1	3	
	neg.	3	1	_	9	7	

Accuracy both 8/20 = 0.4Precision 7/16 = 0.44 and 1/4 = 0.25Recall 7/10 = 0.7 and 1/10 = 0.1F-score 0.54 and 0.14

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Confusion matrix

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• A confusion matrix is often useful for multi-class classification tasks

		true o		
		negative	neutral	positive
predicted	negative	10	3	4
	neutral	2	12	8
	positive	0	7	7

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- Are the classes balanced?
- What is the accuracy?
- What is per-class, and averaged precision/recall?

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Performance metrics a summary

- Accuracy does not reflect the classifier performance when class distribution is skewed
- Precision and recall are binary and asymmetric
- For multi-class problems, calculating accuracy is straightforward, but others measures need averaging
- These are just the most common measures, there are more
- You should understand what these metrics measure, and use/report the metric that is useful for the purpose

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Example: back to the 'dummy' search engine

• For a query - 1000 000 documents - 1000 relevant documents accuracy = $\frac{999\,000}{1\,000\,000} = 99.90\,\%$ precision = $\frac{0}{1\,000\,000} = 0\,\%$ recall = $\frac{0}{1\,000\,000} = 0\,\%$

Precision and recall are asymmetric, the choice of the 'positive' class is important.

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Multi-class evaluation

- For multi-class problems, it is common to report average precision/recall/f-score
- For C classes, averaging can be done two ways:

$$precision_{M} = \frac{\sum_{i}^{C} \frac{TP_{i}}{TP_{i}+FP_{i}}}{C} \qquad recall_{M} = \frac{\sum_{i}^{C} \frac{TP_{i}}{TP_{i}+FN_{i}}}{C}$$
$$precision_{\mu} = \frac{\sum_{i}^{C} TP_{i}}{TP_{i}} \qquad recall_{\mu} = \frac{\sum_{i}^{C} TP_{i}}{TP_{i}}$$

$$\operatorname{recision}_{\mu} = \frac{\sum_{i}^{C} \mathsf{TP}_{i}}{\sum_{i}^{C} \mathsf{TP}_{i} + \mathsf{FP}_{i}} \qquad \operatorname{recall}_{\mu} = \frac{\sum_{i}^{C} \mathsf{TP}_{i}}{\sum_{i}^{C} \mathsf{TP}_{i} + \mathsf{FN}_{i}}$$

 $(M = macro, \mu = micro)$

 The averaging can also be useful for binary classification, if there is no natural positive class

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Precision-recall trade-off

- Increasing precision (e.g., by changing a hyperparameter) results in decreasing recall
- Precision–recall graphs are useful for picking the correct models
- Area under the curve (AUC) is another indication of success of a classifier



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Summary

- We discussed three basic classification techniques: perceptron, logistic regression, naive Bayes
- We left out many others: SVMs, decision trees, ...
- We also did not discuss a few other interesting cases,
- including multi-label classification
- We will discuss some (non-linear) classification methods next

Next

Wed ML evaluation, quick summary so far

Mon Introduction to neural networks

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Additional reading, references, credits

- Hastie, Tibshirani, and Friedman (2009) covers logistic regression in section 4.4 and perceptron in section 4.5
- Jurafsky and Martin (2009) explains it in section 6.6, and it is moved to its own chapter (7) in the draft third edition
- Hastie, Trevor, Robert Tibshirani, and Jerome Friedman (2009). The Elements of Statistical Learning: Data Mining, Inference, and Prediction. Second. Springer series in statistics. Springer-Verlag New York. sas: 9780387848587. uni http://web.stanford.edu/-hastie/ElesStatLearn/.
- Jurafsky, Daniel and James H. Martin (2009). Speech and Language Processing: An Introduction to Natural Language Processing, Computational Linguistics, and Speech Recognition. second. Pearson Prentice Hall. isas: 978-0-13-504196-3.
- P Minsky, Marvin and Seymour Papert (1969). Perceptrons: An introduction to computational geometry. MIT Press.
- Rosenblatt, Frank (1958). "The perceptron: a probabilistic model for information storage and organization in the brain.". In: Psychological review 65.6, pp. 386-408.

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